

ON POLYNOMIAL APPROXIMATIONS TO SOLUTIONS OF IMPLICIT DIFFERENTIAL EQUATIONS

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[Received: April 4, 2002]

Abstract. In this paper the possibility to present by a polynomial an independent variable for the approximate solutions of the systems of implicit ordinary differential equations under multi-point boundary conditions is substantiated.

Mathematical Subject Classification: 34A09, 34B10

Keywords: multi-point boundary value problems, implicit differential equations, numerical-analytic method, determining equation.

1. Introduction

There is a large number of methods which mathematicians elaborated for studying boundary value problems (BVPs). In the papers [1], [2] the numerical-analytic method based upon successive approximations was introduced. The polynomial version of this method in which the successive approximations are polynomials was proposed in [1] and then developed in [3], [4] for three- and multi-point boundary conditions. In this paper the issue of existence and approximate construction of the solutions of multi-point boundary conditions for the systems of implicit ordinary differential equations of the first order are studied by using polynomial approximations.

2. Construction of successive polynomial approximations

Let us consider a system of implicit equations

$$\frac{dx}{dt} = f\left(t, x, \frac{dx}{dt}\right), \quad (2.1)$$

with a multi-point boundary conditions

$$A_0x(0) + \sum_{k=1}^q A_kx(t_k) + A_{q+1}x(T) = d, \quad (2.2)$$

where $x, d \in R^n$, $f : [0, T] \times D_1 \times D_2 \rightarrow R^n$, D_1, D_2 are closed bounded domains in R^n , $0 = t_0 < t_1 < \dots < t_q < t_{q+1} = T$, A_k ($k = 0, 1, \dots, q + 1$) - are $n \times n$ matrices

so that $\det \left[\sum_{k=1}^{q=1} A_k t_k \right] \neq 0$.

First of all we will introduce some notations [1].

It is known that for $f(t) \in C[0, T]$ there is a unique polynomial $P_m^0(t)$ among all the polynomials $P_m(t)$ with no more than m degree which is the best approximation for $f(t)$:

$$E_m(f) \equiv \|f(t) - P_m^0(t)\| = \inf_{P_m(t)} \|f(t) - P_m(t)\|.$$

Let us set in the interval $[0, T]$ the nodes

$$\tau_i = \frac{T}{2} \left(\cos \frac{(2i-1)\pi}{2(p+1)} + 1 \right), \quad i = 1, 2, \dots, p+1, \quad (2.3)$$

which are obtained by the substitution $\tau = \frac{T}{2} (\tau' + 1)$ from the corresponding zeroes $\tau'_i \in [-1, 1]$ of the Chebyshev polynomials

$$T_{p+1}(t) = \cos((p+1) \arccos t).$$

For arbitrary continuous function $x_r(t)$ by $f^p(t, x_r(t), y_r(t))$ we denote the Lagrange interpolation polynomial with p degree and with respect to the points (2.3):

$$f^p(t, x_r(t, x_0), y_r(t, x_0)) = (f_1^p(t, x_r(t, x_0), y_r(t, x_0)), \dots, f_n^p(t, x_r(t, x_0), y_r(t, x_0))),$$

where $y_r(t) := \frac{dx_r(t)}{dt}$, $f_j^p(t, x_r(t, x_0), y_r(t, x_0)) = a_{0j}^r + a_{1j}^r t + \dots + a_{pj}^r$, $j =$

$1, 2, \dots, n$, $f_j^p(\tau_i, x_r(\tau_i), y_r(\tau_i)) = f_j(\tau_i, x_r(\tau_i), y_r(\tau_i))$, $i = 1, 2, \dots, p+1$.

Let us denote by

$$\bar{\mathcal{L}}(f, x, y, t, x_0) = f(t, x(t, x_0), y(t, x_0)) - \frac{1}{T} \int_0^T f(s, x(s, x_0), y(s, x_0)) ds,$$

$$\mathcal{L}(f, x, y, t, x_0) = \int_0^t \left(f(\tau, x(\tau, x_0), y(\tau, x_0)) - \frac{1}{T} \int_0^T f(s, x(s, x_0), y(s, x_0)) ds \right) d\tau.$$

We assume that the following conditions hold for the BVP (2.1), (2.2):

- a) the vector-function $f(t, x, y)$ is continuous in $\Omega = [0, T] \times D_1 \times D_2$ (and therefore it is bounded by some vector M) and Lipschitzian in x and y , i.e.,

$$|f(t, x, y)| \leq M, \quad |f(t, x, y) - f(t, \bar{x}, \bar{y})| \leq K_1 |x - \bar{x}| + K_2 |y - \bar{y}|, \quad (2.4)$$

where M and $n \times n$ matrices K_1, K_2 have non-negative components. The absolute value sign and the inequalities we understand component-wise;

- b) domains D_1 and D_2 satisfy the conditions

$$D_{\beta_1} := \{x \in R^n \mid B(x, \beta_1(x)) \subset D_1\} \neq \emptyset, \quad B(0, \beta_2(x)) \subset D_2,$$

where $B(x, \rho(x))$ is the ball of radius $\rho(x)$ with center x and

$$\beta_1(x) = \left(\frac{T}{2}E + G\right) \cdot (M' + L_p) + T|d(x)|, \quad G = T \cdot \sum_{k=1}^q |HA_k| \cdot \alpha_1(t_k),$$

$$\beta_2(x) = 2(M + L_p) + \frac{1}{T}G(M' + L_p) + |d(x)|, \quad H = \left[\sum_{k=1}^{q+1} A_k t_k\right]^{-1},$$

$$d(x) = H \cdot \left(d - \sum_{k=0}^{q+1} A_k x\right), \quad \alpha_1(t) = 2t \left(1 - \frac{t}{T}\right),$$

$$M' = \frac{1}{2} \left[\max_{(t,x,y) \in \Omega} f(t, x, y) - \min_{(t,x,y) \in \Omega} f(t, x, y) \right],$$

$$\begin{aligned} L_p &= (5 + \lg p) \max_r E_p (f(t, x_r^{p+1}(t, x_0), y_r^p(t, x_0))) = \\ &= (5 + \lg p) \cdot \left(\max_r E_p (f_1(t, x_r^{p+1}(t, x_0), y_r^p(t, x_0))), \dots \right. \\ &\quad \left. \dots, \max_r E_p (f_n(t, x_r^{p+1}(t, x_0), y_r^p(t, x_0))) \right); \end{aligned}$$

c) the eigenvalues $\lambda_j(Q)$ of the matrix $Q = K_1 \left(\frac{T}{2}E + G\right) + K_2 \left(2E + \frac{1}{T}G\right)$ satisfy the inequalities

$$|\lambda_j(q)| < 1, \quad j = 1, \dots, n. \tag{2.5}$$

Let us introduce the sequence of polynomials with $p + 1$ degree

$$\begin{aligned} x_m^{p+1}(t, x_0) &= x_0 + \mathcal{L} \left(f^p, x_{m-1}^{p+1}, y_{m-1}^p, t, x_0 \right) + tHd(x_0) - \\ &- tH \sum_{k=1}^q A_k \mathcal{L} \left(f^p, x_{m-1}^{p+1}, y_{m-1}^p, t_k, x_0 \right), \quad x_0^{p+1}(t, x_0) = x_0, \quad m = 1, 2, \dots \end{aligned} \tag{2.6}$$

Their derivatives look as follows:

$$\begin{aligned} y_m^p(t, x_0) &= \overline{\mathcal{L}} \left(f^p, x_{m-1}^{p+1}, y_{m-1}^p, t, x_0 \right) + Hd(x_0) - \\ &- H \sum_{k=1}^q A_k \mathcal{L} \left(f^p, x_{m-1}^{p+1}, y_{m-1}^p, t_k, x_0 \right), \quad y_0^p(t, x_0) = 0, \quad m = 1, 2, \dots \end{aligned} \tag{2.7}$$

Here the above index means that this expression is a polynomials of a correspondent degree. It is easy to see that all the members of the sequence (2.6) satisfy the boundary condition (2.2) for arbitrary $x_0 \in D_{\beta_1}$.

The next theorem establishes the convergence of the sequence (2.6) and the properties of the limit functions.

Theorem 1. *Let BVP (2.1), (2.2) satisfy the conditions a)-c). Then:*

(1) *the sequences (2.6) and (2.7) converge to the functions $x^*(t, x_0)$ and $y^*(t, x_0)$, respectively, as $m \rightarrow \infty$, uniformly in $(t, x_0) \in [0, T] \times D_{\beta_1}$:*

$$x^*(t, x_0) = \lim_{m \rightarrow \infty} x_m^{p+1}(t, x_0), \quad y^*(t, x_0) = \lim_{m \rightarrow \infty} y_m^p(t, x_0),$$

where $y^*(t, x_0) = \frac{dx^*(t, x_0)}{dt}$;

(2) the limit function $x^*(t, x_0)$ satisfies the "perturbed" BVP

$$\begin{cases} \frac{dx}{dt} = f(t, x, \frac{dx}{dt}) + \Delta(x_0), \\ A_0x(0) + \sum_{k=1}^q A_kx(t_k) + A_{q+1}x(T) = d, \end{cases} \quad (2.8)$$

where

$$\Delta(x_0) = -\frac{1}{T} \int_0^T f^p(s, x^*(s, x_0), y^*(s, x_0)) ds + Hd(x_0) - H \sum_{k=1}^q A_k \mathcal{L}(f^p, x^*, y^*, t_k, x_0), \quad (2.9)$$

with the initial value $x^*(0, x_0) = x_0$;

(3) the following error estimations hold:

$$|x^*(t, x_0) - x_m^{p+1}(t, x_0)| \leq (\alpha_1(t)E + G) \cdot W_{m-1}^p, \quad (2.10)$$

$$|y^*(t, x_0) - y_m^p(t, x_0)| \leq \left(2E + \frac{1}{T}G\right) \cdot W_{m-1}^p, \quad (2.11)$$

where

$$W_{m-1}^p = \left[\sum_{i=0}^{m-1} Q^i \right] \cdot L_p + Q^{m-1}(E - Q)^{-1}.$$

$$\cdot \left[K_1 \left\{ \left(\frac{T}{2}E + G\right) M' + T|d(x_0)| \right\} + K_2 \left\{ 2M + \frac{1}{T}GM' + |d(x_0)| \right\} \right].$$

Proof. In addition to (2.6), (2.7) let us introduce the sequence of functions.

$$x_m(t, x_0) = x_0 + \mathcal{L}(f, x_{m-1}, y_{m-1}, t, x_0) + tHd(x_0) - tH \sum_{k=1}^q A_k \mathcal{L}(f, x_{m-1}, y_{m-1}, t_k, x_0), \quad x_0(t, x_0) = x_0, \quad m = 1, 2, \dots, \quad (2.12)$$

$$y_m(t, x_0) := \frac{dx_m(t, x_0)}{dt} = \bar{\mathcal{L}}(f, x_{m-1}, y_{m-1}, t, x_0) + Hd(x_0) - H \sum_{k=1}^q A_k \mathcal{L}(f, x_{m-1}, y_{m-1}, t_k, x_0), \quad y_0(t, x_0) = 0, \quad m = 1, 2, \dots \quad (2.13)$$

Also we introduce some notations:

$$x_m := x_m(t, x_0), \quad x_m^{p+1} := x_m^{p+1}(t, x_0), \quad r_{m+1}(t, x_0) := |x_{m+1}(t, x_0) - x_m(t, x_0)|,$$

$$y_m := y_m(t, x_0), \quad y_m^p := y_m^p(t, x_0), \quad \hat{r}_{m+1}(t, x_0) := |y_{m+1}(t, x_0) - y_m(t, x_0)|.$$

We note [1] that

$$|f^p(t, x_m^{p+1}, y_m^p) - f(t, x_m^{p+1}, y_m^p)| \leq L_p, \quad (2.14)$$

and making use of (2.4) we get

$$\begin{aligned} |f^p(t, x_m^{p+1}, y_m^p) - f(t, x_m, y_m)| &\leq |f^p(t, x_m^{p+1}, y_m^p) - f(t, x_m^{p+1}, y_m^p)| + \\ &+ |f(t, x_m^{p+1}, y_m^p) - f(t, x_m, y_m)| \leq L_p + K_1 |x_m^{p+1} - x_m| + K_2 |y_m^p - y_m|. \end{aligned} \quad (2.15)$$

Using Lemma 3 of [5] we have that

$$|\mathcal{L}(f, x, y, t, x_0)| \leq \alpha_1(t)M' \leq \frac{T}{2}M', \quad (2.16)$$

$$\left| TH \sum_{k=1}^q A_k \mathcal{L}(f, x, y, t_k, x_0) \right| \leq GM', \quad (2.17)$$

$$|\mathcal{L}(f^p, x_m^{p+1}, y_m^p, t, x_0) - \mathcal{L}(f, x_m^{p+1}, y_m^p, t, x_0)| \leq \alpha_1(t)L_p, \quad (2.18)$$

$$\left| TH \sum_{k=1}^q A_k [\mathcal{L}(f^p, x_m^{p+1}, y_m^p, t_k, x_0) - \mathcal{L}(f, x_m^{p+1}, y_m^p, t_k, x_0)] \right| \leq GL_p. \quad (2.19)$$

We have to show that (2.6) is a Cauchy sequence in the space of continuous vector functions. To begin with, we establish for arbitrary $(t, x_0) \in [0, T] \times D_{\beta_1}$, and $m = 0, 1, 2, \dots$ that $x_m^{p+1}(t, x_0) \in D_1$ and $y_m^p(t, x_0) \in D_2$ by using (2.16)-(2.19):

$$\begin{aligned} |x_1^{p+1} - x_0| &\leq \left| \mathcal{L}(f^p, x_0^{p+1}, y_0^p, t, x_0) \right| + \left| TH \sum_{k=1}^q A_k \mathcal{L}(f^p, x_0^{p+1}, y_0^p, t_k, x_0) \right| + \\ &+ T|d(x_0)| \leq \left| \mathcal{L}(f^p, x_0^{p+1}, y_0^p, t, x_0) - \mathcal{L}(f, x_0, y_0, t, x_0) \right| + |\mathcal{L}(f, x_0, y_0, t, x_0)| + \\ &+ T|d(x_0)| + \left| TH \sum_{k=1}^q A_k [\mathcal{L}(f^p, x_0^{p+1}, y_0^p, t_k, x_0) - \mathcal{L}(f, x_0, y_0, t_k, x_0)] \right| + \\ &+ \left| TH \sum_{k=1}^q A_k \mathcal{L}(f, x_0, y_0, t_k, x_0) \right| \leq (\alpha_1(t)E + G)(L_p + M') + T|d(x_0)| \leq \beta_1(x_0), \\ &+ T|d(x_0)| \leq \left| \mathcal{L}(f^p, x_0^{p+1}, y_0^p, t, x_0) - \mathcal{L}(f, x_0, y_0, t, x_0) \right| + |\mathcal{L}(f, x_0, y_0, t, x_0)| + \\ &+ T|d(x_0)| + \left| TH \sum_{k=1}^q A_k [\mathcal{L}(f^p, x_0^{p+1}, y_0^p, t_k, x_0) - \mathcal{L}(f, x_0, y_0, t_k, x_0)] \right| + \\ &+ \left| TH \sum_{k=1}^q A_k \mathcal{L}(f, x_0, y_0, t_k, x_0) \right| \leq (\alpha_1(t)E + G)(L_p + M') + T|d(x_0)| \leq \beta_1(x_0), \\ |y_1^p| &\leq \left| \bar{\mathcal{L}}(f^p, x_0^{p+1}, y_0^p, t, x_0) \right| + |d(x_0)| + \left| H \sum_{k=1}^q A_k \mathcal{L}(f^p, x_0^{p+1}, y_0^p, t_k, x_0) \right| \leq \\ &\leq \left| \bar{\mathcal{L}}(f^p, x_0^{p+1}, y_0^p, t, x_0) - \bar{\mathcal{L}}(f, x_0, y_0, t, x_0) \right| + \left| \bar{\mathcal{L}}(f, x_0, y_0, t, x_0) \right| + |d(x_0)| + \\ &+ \left| H \sum_{k=1}^q A_k [\mathcal{L}(f^p, x_0^{p+1}, y_0^p, t_k, x_0) - \mathcal{L}(f, x_0, y_0, t_k, x_0)] \right| + \\ &+ \left| H \sum_{k=1}^q A_k \mathcal{L}(f, x_0, y_0, t_k, x_0) \right| \leq 2(M + L_p) + G(M' + L_p) + |d(x_0)| \leq \beta_2(x_0). \end{aligned}$$

It follows that $x_1^{p+1}(t, x_0) \in D_1$, $y_1^p(t, x_0) \in D_2$. By induction in a similar way we can establish that

$$|x_m^{p+1} - x_0| \leq \beta_1(x_0), \quad |y_m^p| \leq \beta_2(x_0).$$

Now we consider the differences $x_m - x_m^{p+1}$ and $y_m - y_m^p$. For $m = 1$ we have

$$\begin{aligned} |x_1 - x_1^{p+1}| &\leq \left| \mathcal{L}(f, x_0, y_0, t, x_0) - \mathcal{L}(f^p, x_0^{p+1}, y_0^p, t, x_0) \right| + \\ &+ \left| TH \sum_{k=1}^q A_k \left[\mathcal{L}(f, x_0, y_0, t_k, x_0) - \mathcal{L}(f^p, x_0^{p+1}, y_0^p, t_k, x_0) \right] \right| \leq \end{aligned} \quad (2.20)$$

$$\leq (\alpha_1(t)E + G) L_p,$$

$$\begin{aligned} |y_1 - y_1^p| &\leq \left| \bar{\mathcal{L}}(f, x_0, y_0, t, x_0) - \bar{\mathcal{L}}(f^p, x_0^{p+1}, y_0^p, t, x_0) \right| + \\ &+ \left| H \sum_{k=1}^q A_k \left[\mathcal{L}(f, x_0, y_0, t_k, x_0) - \mathcal{L}(f^p, x_0^{p+1}, y_0^p, t_k, x_0) \right] \right| \leq \end{aligned} \quad (2.21)$$

$$\leq (2E + \frac{1}{T}G) L_p.$$

Using (2.14)-(2.21) and Lemma 4 of [5] we get

$$\begin{aligned} |x_2 - x_2^{p+1}| &\leq \left| \mathcal{L}(f, x_1, y_1, t, x_0) - \mathcal{L}(f^p, x_1^{p+1}, y_1^p, t, x_0) \right| + \\ &+ \left| TH \sum_{k=1}^q A_k \left[\mathcal{L}(f, x_1, y_1, t_k, x_0) - \mathcal{L}(f^p, x_1^{p+1}, y_1^p, t_k, x_0) \right] \right| \leq \\ &\leq [\alpha_1(t)E + K_1(\alpha_2(t)E + \alpha_1(t)G) + \alpha_1(t)K_2(2E + \frac{1}{T}G)] L_p + \\ &+ \left| TH \sum_{k=1}^q A_k [\alpha_1(t_k)E + K_1(\alpha_2(t_k)E + \alpha_1(t_k)G) + \alpha_1(t_k)K_2(2E + \frac{1}{T}G)] L_p \right| \leq \\ &\leq (\alpha_1(t)E + G) [E + K_1(\frac{T}{3}E + G) + K_2(2E + \frac{1}{T}G)] L_p \leq \\ &\leq (\alpha_1(t)E + G) [E + Q] L_p, \\ |y_2 - y_2^p| &\leq \left| \bar{\mathcal{L}}(f, x_1, y_1, t, x_0) - \bar{\mathcal{L}}(f^p, x_1^{p+1}, y_1^p, t, x_0) \right| + \\ &+ \left| H \sum_{k=1}^q A_k \left[\mathcal{L}(f, x_1, y_1, t_k, x_0) - \mathcal{L}(f^p, x_1^{p+1}, y_1^p, t_k, x_0) \right] \right| \leq \\ &\leq 2 \max_{t \in [0, T]} |f(t, x_1, y_1) - f^p(t, x_1^{p+1}, y_1^p)| + \\ &+ \left| H \sum_{k=1}^q A_k \left| \mathcal{L}_1(f, x_1, y_1, t_k, x_0) - \mathcal{L}_1(f^p, x_1^{p+1}, y_1^p, t_k, x_0) \right| \right| \leq \\ &\leq (2E + \frac{1}{T}G) [E + Q] L_p. \end{aligned}$$

We can obtain by induction that

$$|x_m(t, x_0) - x_m^{p+1}(t, x_0)| \leq (\alpha_1(t)E + G) \left[\sum_{i=1}^{m-1} Q^i \right] L_p, \quad (2.22)$$

$$|y_m(t, x_0) - y_m^p(t, x_0)| \leq \left(2E + \frac{1}{T}G \right) \left[\sum_{i=1}^{m-1} Q^i \right] L_p. \quad (2.23)$$

Now we have to estimate $r_{m+1}(t, x_0)$ and $\widehat{r}_{m+1}(t, x_0)$ for every $m = 0, 1, 2, \dots$ by using Lemmas 3 and 4 of [5]:

$$\begin{aligned}
 r_1(t, x_0) &\leq |\mathcal{L}(f, x_0, y_0, t, x_0)| + T|d(x_0)| + \\
 &+ \left| TH \sum_{k=1}^q A_k \mathcal{L}(f, x_0, y_0, t_k, x_0) \right| \leq \left(\frac{T}{2}E + G \right) M' + T|d(x_0)| \equiv \gamma_1(x_0), \\
 \widehat{r}_1(t, x_0) &\leq |\overline{\mathcal{L}}(f, x_0, y_0, t, x_0)| + |d(x_0)| + \left| H \sum_{k=1}^q A_k \mathcal{L}(f, x_0, y_0, t_k, x_0) \right| \leq \\
 &\leq 2M + |d(x_0)| + \frac{1}{T}GM' \equiv \gamma_2(x_0), \\
 r_2(t, x_0) &\leq |\mathcal{L}(f, x_1, y_1, t, x_0) - \mathcal{L}(f, x_0, y_0, t, x_0)| + \\
 &+ \left| TH \sum_{k=1}^q A_k [\mathcal{L}(f, x_1, y_1, t_k, x_0) - \mathcal{L}(f, x_0, y_0, t_k, x_0)] \right| \leq \\
 &\leq \left(1 - \frac{t}{T}\right) \int_0^t [K_1 r_1(\tau, x_0) + K_2 \widehat{r}_1(\tau, x_0)] d\tau + \frac{t}{T} \int_t^T [K_1 r_1(\tau, x_0) + K_2 \widehat{r}_1(\tau, x_0)] d\tau + \\
 &+ \left| TH \sum_{k=1}^q A_k \left[\left(1 - \frac{t_k}{T}\right) \int_0^{t_k} [K_1 r_1(\tau, x_0) + K_2 \widehat{r}_1(\tau, x_0)] d\tau + \right. \right. \\
 &\left. \left. + \frac{t_k}{T} \int_{t_k}^T [K_1 r_1(\tau, x_0) + K_2 \widehat{r}_1(\tau, x_0)] d\tau \right] \right| \leq (\alpha_1(t)E + G) \cdot [K_1 \gamma_1(x_0) + K_2 \gamma_2(x_0)],
 \end{aligned}$$

$$\begin{aligned}
 \widehat{r}_2(t, x_0) &\leq |\overline{\mathcal{L}}(f, x_1, y_1, t, x_0) - \overline{\mathcal{L}}(f, x_0, y_0, t, x_0)| + \\
 &+ \left| TH \sum_{k=1}^q A_k [\overline{\mathcal{L}}(f, x_1, y_1, t_k, x_0) - \overline{\mathcal{L}}(f, x_0, y_0, t_k, x_0)] \right| \leq \\
 &\leq 2 \max_{t \in [0, T]} |K_1 r_1(\tau, x_0) + K_2 \widehat{r}_1(\tau, x_0)| + \\
 &+ \left| H \sum_{k=1}^q A_k \left[\left(1 - \frac{t_k}{T}\right) \int_0^{t_k} [K_1 r_1(\tau, x_0) + K_2 \widehat{r}_1(\tau, x_0)] d\tau + \right. \right. \\
 &\left. \left. + \frac{t_k}{T} \int_{t_k}^T [K_1 r_1(\tau, x_0) + K_2 \widehat{r}_1(\tau, x_0)] d\tau \right] \right| \leq \left(2E + \frac{1}{T}G \right) \cdot [K_1 \gamma_1(x_0) + K_2 \gamma_2(x_0)].
 \end{aligned}$$

Similarly,

$$\begin{aligned}
r_3(t, x_0) &\leq \left\{ \left(1 - \frac{t}{T}\right) \int_0^t [K_1(\alpha_1(\tau)E + G) + K_2(2E + \frac{1}{T}G)] d\tau + \right. \\
&\quad \left. + \frac{t}{T} \int_t^T [K_1(\alpha_1(\tau)E + G) + K_2(2E + \frac{1}{T}G)] d\tau + \right. \\
&\quad \left. + \left| TH \sum_{k=1}^q A_k \left[\left(1 - \frac{t_k}{T}\right) \int_0^{t_k} [K_1(\alpha_1(\tau)E + G) + K_2(2E + \frac{1}{T}G)] d\tau + \right. \right. \right. \\
&\quad \left. \left. \left. + \frac{t_k}{T} \int_{t_k}^T [K_1(\alpha_1(\tau)E + G) + K_2(2E + \frac{1}{T}G)] d\tau \right] \right| \right\} \cdot [K_1\gamma_1(x_0) + K_2\gamma_2(x_0)] \leq \\
&\leq (\alpha_1(t)E + G) \cdot Q \cdot [K_1\gamma_1(x_0) + K_2\gamma_2(x_0)],
\end{aligned}$$

$$\begin{aligned}
\hat{r}_3(t, x_0) &\leq \left\{ 2 \max_{t \in [0, T]} |K_1(\alpha_1(\tau)E + G) + K_2(2E + \frac{1}{T}G)| + \right. \\
&\quad \left. + \left| H \sum_{k=1}^q A_k \left[\left(1 - \frac{t_k}{T}\right) \int_0^{t_k} [K_1(\alpha_1(\tau)E + G) + K_2(2E + \frac{1}{T}G)] d\tau + \right. \right. \right. \\
&\quad \left. \left. \left. + \frac{t_k}{T} \int_{t_k}^T [K_1(\alpha_1(\tau)E + G) + K_2(2E + \frac{1}{T}G)] d\tau \right] \right| \right\} \cdot [K_1\gamma_1(x_0) + K_2\gamma_2(x_0)] \leq \\
&\leq (2E + \frac{1}{T}G) \cdot Q \cdot [K_1\gamma_1(x_0) + K_2\gamma_2(x_0)].
\end{aligned}$$

We can show by induction that for arbitrary $m = 0, 1, 2, \dots$

$$r_{m+1}(t, x_0) \leq (\alpha_1(t)E + G) \cdot Q^{m-1} \cdot [K_1\gamma_1(x_0) + K_2\gamma_2(x_0)], \quad (2.24)$$

$$\hat{r}_{m+1}(t, x_0) \leq \left(2E + \frac{1}{T}G\right) \cdot Q^{m-1} \cdot [K_1\gamma_1(x_0) + K_2\gamma_2(x_0)]. \quad (2.25)$$

From (2.24) and assumption c) we obtain the inequality

$$\begin{aligned}
|x_{m+j}(t, x_0) - x_m(t, x_0)| &\leq \sum_{i=0}^{j-1} |x_{m+i+1}(t, x_0) - x_{m+i}(t, x_0)| \leq \\
&\leq \sum_{i=0}^{j-1} r_{m+i+1}(t, x_0) \leq \sum_{i=0}^{j-1} (\alpha_1(t)E + G) Q^{m+i-1} [K_1\gamma_1(x_0) + K_2\gamma_2(x_0)] \leq \quad (2.26) \\
&\leq (\alpha_1(t)E + G) \cdot Q^{m-1} (E - Q)^{-1} \cdot [K_1\gamma_1(x_0) + K_2\gamma_2(x_0)].
\end{aligned}$$

For the derivatives $y_m(t, x_0)$ from (2.25) in a similar way we have:

$$\begin{aligned}
|y_{m+j}(t, x_0) - y_m(t, x_0)| &\leq \\
&\leq (2E + \frac{1}{T}G) Q^{m-1} (E - Q)^{-1} [K_1\gamma_1(x_0) + K_2\gamma_2(x_0)]. \quad (2.27)
\end{aligned}$$

It follows that (2.12) and (2.13) are uniformly convergent sequences:

$$\lim_{m \rightarrow \infty} x_m(t, x_0) = x^*(t, x_0), \quad \lim_{m \rightarrow \infty} y_m(t, x_0) = y^*(t, x_0).$$

Taking the limit as $j \rightarrow \infty$ in (2.26) and (2.27) we get the error estimates

$$|x^*(t, x_0) - x_m(t, x_0)| \leq (\alpha_1(t)E + G) \cdot Q^{m-1} (E - Q)^{-1} \cdot [K_1\gamma_1(x_0) + K_2\gamma_2(x_0)],$$

$$|y^*(t, x_0) - y_m(t, x_0)| \leq (2E + \frac{1}{T}G) \cdot Q^{m-1} (E - Q)^{-1} \cdot [K_1\gamma_1(x_0) + K_2\gamma_2(x_0)].$$

Combining the last two inequalities with (2.22) and (2.23), we get the error estimates (2.10) and (2.11). Passing to the limit as $m \rightarrow \infty$ in (2.6) we obtain that $x^*(t, x_0)$ satisfies the integral equation

$$x(t) = x_0 + \mathcal{L}(f, x, y, t, x_0) + tHd(x_0) - tH \sum_{k=1}^q A_k \mathcal{L}(f, x, y, t_k, x_0).$$

While differentiating it, we get that $x^*(t, x_0)$ is a solution of the perturbed BVP (2.8)-(2.9). □

The following statement gives necessary and sufficient conditions for the existence of a solution of the BVP (2.1)-(2.2).

Theorem 2. *Under the conditions of Theorem 1, the limit function $x^*(t, x_0^*)$ is a solution of the BVP (2.1)-(2.2) if and only if x_0^* verifies the determining equation*

$$\begin{aligned} \Delta(x_0) = & -\frac{1}{T} \int_0^T f(s, x^*(s, x_0), y^*(s, x_0)) ds + Hd(x_0) + \\ & + H \sum_{k=1}^q A_k \mathcal{L}(f, x^*, y^*, t_k, x_0) = 0. \end{aligned} \tag{2.28}$$

Proof. The proof can be carried out in the same way as for the corresponding statements from [2] (Theorem 2.3). □

3. Sufficient existence conditions

Consider the m -th approximation to the determining equation (2.28)

$$\begin{aligned} \Delta_m^p(x_0) = & -\frac{1}{T} \int_0^T f^p(s, x_m^{p+1}(s, x_0), y_m^p(s, x_0)) ds + Hd(x_0) + \\ & + H \sum_{k=1}^q A_k \mathcal{L}(f^p, x_m^{p+1}, y_m^p, t_k, x_0) = 0. \end{aligned} \tag{3.1}$$

Theorem 3. *Suppose that the conditions of Theorem 1 hold. Furthermore, assume that*

- d) *there exists a closed, convex subset $D' = D'_1 \times D'_2 \subset D_1 \times D_2$ so that for arbitrary m and fixed p the approximate determining equation (3.1) has only one solution $x_0 = x_{0m}^p$ with non-zero topological index;*

e) on the boundary ∂D of the subset D the inequality

$$\inf_{x_0 \in \partial D} |\Delta_m^p(x_0)| > \left(E + \frac{1}{T}G\right) W_m^p$$

holds.

Then there exists a solution $x = x^*(t)$ to the BVP (2.1)-2.2) with the initial value $x^*(0) = x_0^*$, where $x_0^* \in D'_1$.

Proof. Similarly to (2.15) and making use of (2.10) and (2.11), we get

$$|f(t, x^*, y^*) - f^p(t, x_m^{p+1}, y_m^p)| \leq \left[K_1 (\alpha_1(t) E + G) + K_2 \left(2E + \frac{1}{T}G \right) \right] W_{m-1}^p + L_p.$$

For the deviation of the exact and approximate determining functions we have that

$$\begin{aligned} |\Delta(x_0) - \Delta_m^p(x_0)| &\leq \frac{1}{T} \int_0^T |f^p(s, x^*(s, x_0), y^*(s, x_0)) - \\ &- f^p(s, x_m^{p+1}(s, x_0), y_m^p(s, x_0))| + H \sum_{k=1}^q A_k |\mathcal{L}(f^p, x^*, y^*, t_k, x_0) - \\ &- \mathcal{L}(f^p, x_m^{p+1}, y_m^p, t_k, x_0)| \leq (E + \frac{1}{T}G) (QW_{m-1}^p + L_p) \leq (E + \frac{1}{T}G) W_m^p. \end{aligned}$$

Similarly to Theorem 3.1 of [2], one can prove that the vector fields $\Delta(x_0)$ and $\Delta_m^p(x_0)$ are homotopic, which completes the proof of Theorem 3. \square

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